

분리논리 자동정리증명기 개발 (A Theorem Prover for Separation Logic)

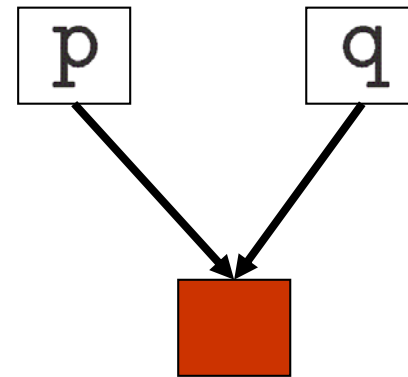
박성우
POSTECH

제9회 소프트웨어무결점연구센터 워크숍
2013년 1월 31일

Shared Mutable Data Structures

- An updatable field can be referenced from more than one point.

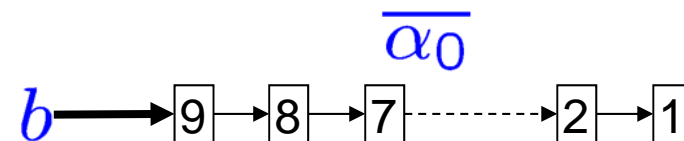
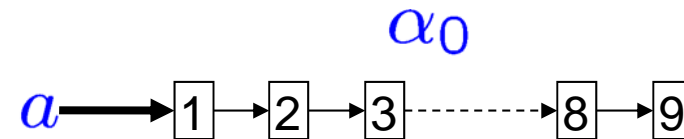
```
*p := 0;  
*q := 1;  
if (*p = 0)  
    return true;  
else  
    return false;
```



- Hoare logic fails to scale to programs of even moderate size.

Specification of In-place List Reversal

```
@pre:  list  $\alpha_0$  a
b := nil;
while (a != nil) do
  k := [a + 1];
  [a + 1] := b;
  b := a;
  a := k;
end while;
@post: list  $\overline{\alpha_0}$  b
```



Loop Invariant in Hoare Logic

@pre list α_0 a

$b := \text{nil};$

@L: $\exists \alpha, \beta. \text{list } \alpha \ a \wedge \text{list } \beta \ b \wedge \overline{\alpha_0} = \overline{\alpha} \cdot \beta$

while ($a \neq \text{nil}$) do

$k := [a + 1];$

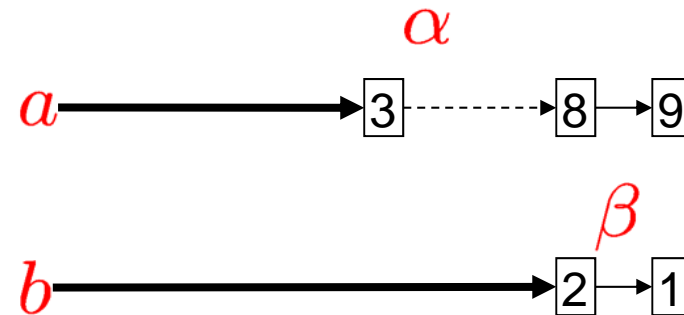
$[a + 1] := b;$

$b := a;$

$a := k;$

end while;

@post list $\overline{\alpha_0}$ b



- However, lists a and b must be disjoint.

Complex Loop Invariant in Hoare Logic

@pre list α_0 a

$b := \text{nil};$

@L: $\exists \alpha, \beta. \text{list } \alpha \ a \wedge \text{list } \beta \ b \wedge \overline{\alpha_0} = \overline{R} \cdot \beta$

$\wedge (\forall k. \text{reachable}(a, k) \wedge \text{reachable}(b, k) \supset k = \text{nil})$

while ($a \neq \text{nil}$) do

$k := [a + 1];$

$[a + 1] := b;$

$b := a;$

$a := k;$

end while;

@post list $\overline{\alpha_0}$ b



Lists a and b are disjoint.

Loop Invariant in Separation Logic

@pre list α_0 a

$b := \text{nil};$

@L: $\exists \alpha, \beta. \text{list } \alpha \ a \star \text{list } \beta \ b \wedge \overline{\alpha_0} = \overline{\alpha} \cdot \beta$

while ($a \neq \text{nil}$) do

$k := [a + 1];$

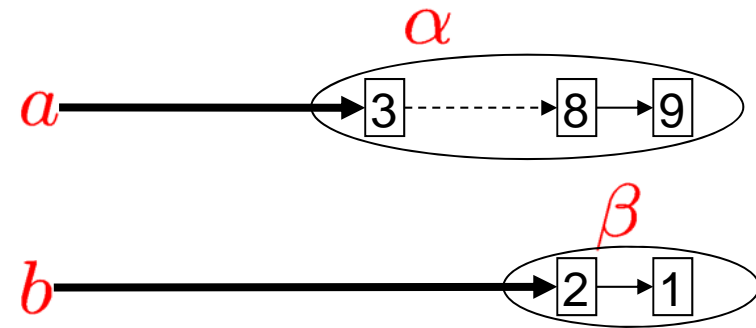
$[a + 1] := b;$

$b := a;$

$a := k;$

end while;

@post list $\overline{\alpha_0}$ b



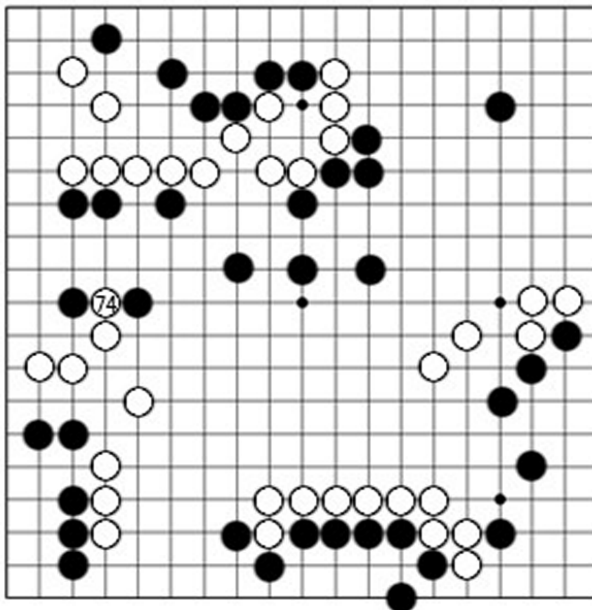
- \star = separating conjunction
 - describes two disjoint memory portions

Frame Rule in Separation Logic

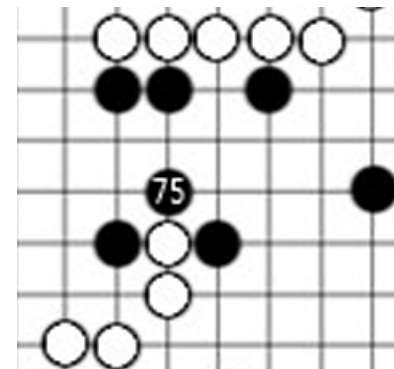
- Supports local reasoning

$$\frac{\{A\} \text{ Program } \{B\}}{\{A \star C\} \text{ Program } \{B \star C\}}$$

where Program does not access variables in C



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Logical Connectives in Separation Logic

- Separating conjunction

$$A \star B$$

- The current heap can be partitioned into two separate heaps;
- A holds for one, and B holds for the other.



- Separating implication

$$A \multimap B$$

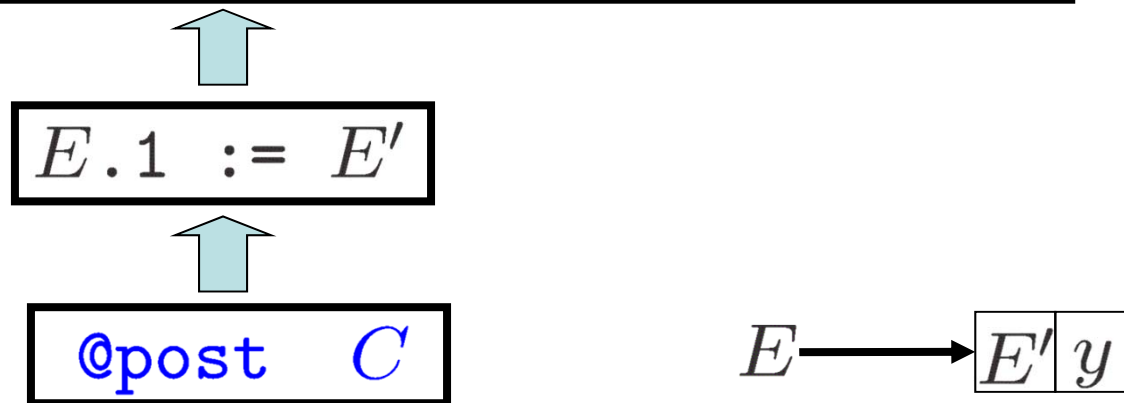
- If the current heap is extended with a separate heap for which A holds,
- then B holds for the combined heap.



Separating Implication $A \multimap B$

- Essential to building a complete verification system
 - with backward reasoning by weakest precondition generation

$$\text{WP: } \exists x, y. (E \mapsto x, y) \star ((E \mapsto E', y) \multimap C)$$



- No existing verification tools fully support $A \multimap B$.
 - Smallfoot, Space Invader, THOR, SLayer, HIP, VeriFast, jStar, Xisa, ...

Goal

- Build a theorem prover for full separation logic
 - with separating conjunction \star
 - **also with separating implication** $\rightarrow\star$

This incompleteness could be dealt with if we instead used the backwards-running weakest preconditions of Separation Logic [4]. Unfortunately, there is no existing automatic theorem prover which can deal with the form of these assertions (which use quantification and the separating implication $\rightarrow\star$). If there were such a prover, we would be eager consumers of it.

Symbolic Execution with Separation Logic.
Josh Berdine and Cristiano Calcagno and Peter O'Hearn. APLAS'05.

- Schorr-Waite Algorithm의 기계적 검증

Contents

- Introduction ✓
- **Theorem prover for Boolean BI**
- Theorem prover for separation logic

Building a Theorem Prover for Boolean BI

- Boolean BI (Bunched Implications)
 - underlying theory of separation logic
 - classical logic extended with \star and \multimap

$$A ::= P \mid \top \mid \neg A \mid A \wedge B \mid \bot \mid A \star B \mid A \multimap B$$

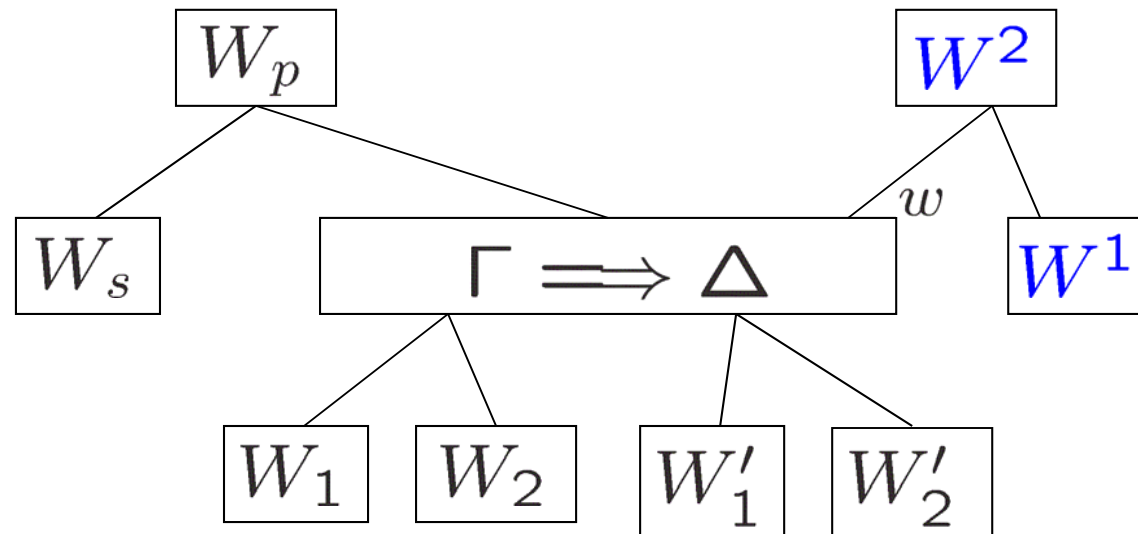
- S_{BBI}
 - nested sequent calculus for Boolean BI

Nested Sequents with Graph Structures

- Classical logic + $A \star B + A \rightarrow \star B$

formula	A	$::=$	$P \mid \perp \mid \neg A \mid A \vee B \mid A \star B$
truth ctx.	Γ	$::=$	$\cdot \mid \Gamma; S$
false. ctx.	Δ	$::=$	$\cdot \mid \Delta; A$
node state	S	$::=$	$A \mid \emptyset_m \mid W_1, W_2 \mid W^1 \langle\langle W^2 \rangle\rangle$
sequent	W	$=$	$\Gamma \Longrightarrow \Delta$

$W^1 \langle\langle W^2 \rangle\rangle$: a sibling sequent W^1 and a common parent sequent W^2



S_{BBI}: Nested Sequent Calculus for Boolean BI

Structural rules:

$$\frac{\Gamma \Rightarrow \Delta}{\Gamma; S \Rightarrow \Delta} WL_S \quad \frac{\Gamma \Rightarrow \Delta}{\Gamma \Rightarrow \Delta; A} WR_S \quad \frac{\Gamma; S; S \Rightarrow \Delta}{\Gamma; S \Rightarrow \Delta} CL_S \quad \frac{\Gamma \Rightarrow \Delta; A; A}{\Gamma \Rightarrow \Delta; A} CR_S \quad \frac{\Gamma; W', W \Rightarrow \Delta}{\Gamma; W, W' \Rightarrow \Delta} EC_S$$

$$\frac{\Gamma; W_1, (W_2, W_3 \Rightarrow \cdot) \Rightarrow \Delta}{\Gamma; (W_1, W_2 \Rightarrow \cdot), W_3 \Rightarrow \Delta} EA_S \quad \frac{\Gamma_1; (\Gamma_2 \Rightarrow \Delta_2), (\emptyset_m \Rightarrow \cdot) \Rightarrow \Delta_1}{\Gamma_1; \Gamma_2 \Rightarrow \Delta_1; \Delta_2} \emptyset_m U_S \quad \frac{\Gamma_1; \Gamma_2 \Rightarrow \Delta_1; \Delta_2}{\Gamma_1; (\Gamma_2 \Rightarrow \Delta_2), (\emptyset_m \Rightarrow \cdot) \Rightarrow \Delta_1} \emptyset_m D_S$$

Traverse rules:

$$\frac{\Gamma_{c1}; (\Gamma_{c2} \Rightarrow \Delta_{c2}) \langle \Gamma \Rightarrow \Delta \rangle \Rightarrow \Delta_{c1}}{\Gamma; (\Gamma_{c1} \Rightarrow \Delta_{c1}), (\Gamma_{c2} \Rightarrow \Delta_{c2}) \Rightarrow \Delta} TC_S \quad \frac{\Gamma_p; (\Gamma \Rightarrow \Delta), (\Gamma_s \Rightarrow \Delta_s) \Rightarrow \Delta_p}{\Gamma; (\Gamma_s \Rightarrow \Delta_s) \langle \Gamma_p \Rightarrow \Delta_p \rangle \Rightarrow \Delta} TP_S$$

Logical rules:

$$\frac{}{A \Rightarrow A} Init_S \quad \frac{}{\perp \Rightarrow \cdot} \perp L_S \quad \frac{\Gamma \Rightarrow \Delta}{\Gamma \Rightarrow \Delta; \perp} \perp R_S \quad \frac{\Gamma \Rightarrow \Delta; A}{\Gamma; \neg A \Rightarrow \Delta} \neg L_S \quad \frac{\Gamma; A \Rightarrow \Delta}{\Gamma \Rightarrow \Delta; \neg A} \neg R_S \quad \frac{\Gamma_1; A \Rightarrow \Delta_1 \quad \Gamma_2; B \Rightarrow \Delta_2}{\Gamma_1; \Gamma_2; A \vee B \Rightarrow \Delta_1; \Delta_2} \vee L_S$$

$$\frac{\Gamma \Rightarrow \Delta; A; B}{\Gamma \Rightarrow \Delta; A \vee B} \vee R_S \quad \frac{\Gamma; \emptyset_m \Rightarrow \Delta}{\Gamma; \mathbf{I} \Rightarrow \Delta} \mathbf{I} L_S \quad \frac{}{\emptyset_m \Rightarrow \mathbf{I}} \mathbf{I} R_S \quad \frac{\Gamma; (A \Rightarrow \cdot), (B \Rightarrow \cdot) \Rightarrow \Delta}{\Gamma; A \star B \Rightarrow \Delta} \star L_S$$

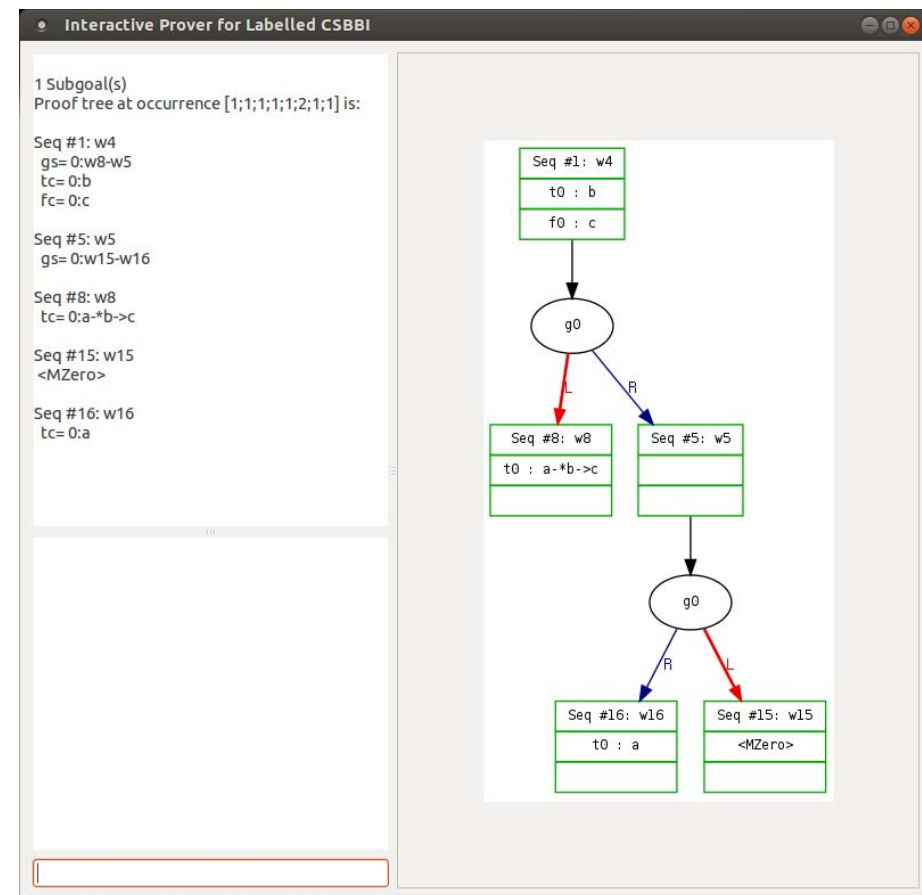
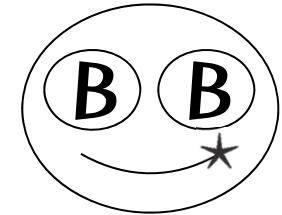
$$\frac{\Gamma_1 \Rightarrow \Delta_1; A \quad \Gamma_2 \Rightarrow \Delta_2; B}{(\Gamma_1 \Rightarrow \Delta_1), (\Gamma_2 \Rightarrow \Delta_2) \Rightarrow A \star B} \star R_S \quad \frac{\Gamma_1 \Rightarrow \Delta_1; A \quad \Gamma_2; B \Rightarrow \Delta_2}{(\Gamma_1 \Rightarrow \Delta_1) \langle \Gamma_2 \Rightarrow \Delta_2 \rangle; A \multimap B \Rightarrow \cdot} \multimap L_S \quad \frac{\Gamma; (A \Rightarrow \cdot) \langle \cdot \Rightarrow B \rangle \Rightarrow \Delta}{\Gamma \Rightarrow \Delta; A \multimap B} \multimap R_S$$

Theorem (Cut elimination):

If $\Gamma \Rightarrow \Delta; C$ and $\Gamma'; C \Rightarrow \Delta'$, then $\Gamma; \Gamma' \Rightarrow \Delta; \Delta'$.

BBeye: A Theorem Prover for Boolean BI

- Interactive
- Supports both CUI and GUI
- Written in OCaml
- Online demo at <http://pl.postech.ac.kr/BBI/>
- Jonghyun Park, Jeongbong Seo, Sungwoo Park. *A Theorem Prover for Boolean BI*. POPL 2013.
- Now we know how to deal with \multimap .



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- Introduction V
- Theorem prover for Boolean BI V
- **Theorem prover for separation logic**

Separation Logic

- 정의

location	L_1, L_2, L_3, \dots	
expression	E	$::= L_i \mid x \mid a \mid \dots$
location expression	l	$::= L_i \mid x \mid a$
primitive formula	P	$::= [l \mapsto E] \mid E = E \mid \dots$
formula	A, B, C	$::= P \mid \perp \mid \neg A \mid A \vee A \mid$ $\mid \mid A \star A \mid A \multimap A \mid \exists a. A$

- Judgment

$$(S, H) \models A$$

- 문제:

“주어진 formula A 가 모든 stack S 와 모든 heap H 에 대해서 참인지 판별하라”

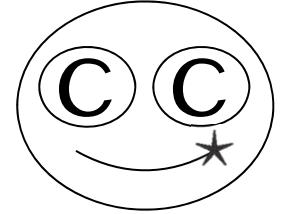
- quantifier 9가 없으면: decidable
- quantifier 9가 있으면: undecidable

Proof System for Separation Logic

- 첫 번째 key idea (from BBeye):
 - use a graph structure of sequents
 - label each sequent with a heap variable.
- 두 번째 key idea
 - 전체 system의 completeness = primitive formula를 다루는 system의 completeness
- 현재 soundness와 completeness 증명 중
 - soundness: proof system은 옳다
 - completeness: 놓치는 경우가 없다

CCeye: A Theorem Prover for Separation Logic

- 현재 설계 중



expression relation	θ	$::=$	$E = E' \mid E \neq E'$
expression relations	Θ	$=$	$\theta_1, \dots, \theta_n$
heap variable	w, u, v		
heap relation	σ	$::=$	$w \dot{=} \epsilon \mid w \not\dot{=} \epsilon \mid w \dot{=} [l \mapsto E] \mid$ $w \not\dot{=} [l \mapsto E] \mid w \dot{=} w' \circ w'' \mid w \dot{=} w'$
heap relations	Σ	$=$	$\sigma_1, \dots, \sigma_n$
truth context	Γ	$::=$	$\cdot \mid \Gamma, A$
falsehood context	Δ	$::=$	$\cdot \mid \Delta, A$
heap sequent	$[\Gamma \Longrightarrow \Delta]^w$		
heap sequents	Π	$=$	$[\Gamma \Longrightarrow \Delta]^w, \dots, [\Gamma' \Longrightarrow \Delta']^{w'}$
world description	$\Theta; \Sigma \parallel \Pi$		

- Challenge: Complexity 문제 처리

謝謝
감사합니다

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